Solution of Parallel Language Equations for Logic Synthesis

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Abstract

The problem of designing a component that combined with a known part of a system, conforms to a given overall specification arises in several applications ranging from logic synthesis to the design of discrete controllers. We cast the problem as solving abstract equations over languages. Language equations can be defined with respect to several language composition operators such as synchronous composition, •, and parallel composition, ⊗; conformity can be checked by language containment. In this paper we address parallel language equations.

Parallel composition arises in the context of modeling delay-insensitive processes and their environments. The parallel composition operator models an exchange protocol by which an input is followed by an output after a finite exchange of internal signals. It abstracts a system with two components with a single message in transit, such that at each instance either the components exchange messages or one of them communicates with its environment, which submits the next external input to the system only after the system has produced an external output in response to the previous input.

We study the most general solutions of the language equation \( A \odot X \subseteq C \), and define the language operators needed to express them. Then we specialize such equations to languages associated with important classes of automata used for modeling systems, e.g., regular languages and FSM languages. In particular, for \( A \odot X \subseteq C \), we give algorithms for computing: the largest FSM language solution, the largest complete solution, and the largest solution whose composition with \( A \) yields a complete FSM language. We solve also FSM equations under bounded parallel composition.

In this paper, we give concrete algorithms for computing such solutions, and state and prove their correctness.

1 Introduction

An important step in the design of complex systems is the decomposition of the system into separate components which interact in some well-defined way. A typical problem is how to design a component that combined with a known part of a system, called the context, conforms to a given overall specification. This arises in several applications ranging from logic synthesis to the design of discrete controllers. There are three key issues to consider: how to model the system, its components and specification, how to model the composition of the components, and how to model the notion of a system conforming.

In general, one can define equations over languages associated with the components of a given system and check conformity by language containment. Two composition operators for abstract languages are: synchronous •, and parallel, ⊗, leading to the synchronous equation \( A \bullet X \subseteq C \) and the parallel equation \( A \odot X \subseteq C \). The theory of equations over languages can be specialized further to languages associated with interesting classes of automata, such as finite automata (FAs) and finite state machines (FSMs). Then the goal is to characterize the solutions of the equations over FSMS \( M_A \bullet M_X \subseteq M_C \) and \( M_A \odot M_X \subseteq M_C \), where \( M_A \) models the context, \( M_C \) the specification and \( M_X \) is an unknown FSM.

In this paper we present a theory for parallel language equations. In particular we show how to compute the largest language solution of \( A \odot X \subseteq C \), the largest FSM language, the largest complete solution, and the largest solution whose composition with the context \( A \) yields a complete FSM language. We solve also equations under bounded parallel composition.

For references on parallel equations see [8] on “asynchronous equations”. In process algebra parallel equations have been solved for processes, which are described by prefix-closed regular languages, over various conformance relations [7, 9, 6]. In this paper we introduce parallel equations over arbitrary languages under language containment, and propose effective procedures for regular languages and languages of FSMS. Some procedures in this paper are based on those proposed in [8] for “asynchronous equations”. Solution of synchronous equations in the context of logic synthesis are surveyed in [4], Chap. 6.

2 Equations over Languages

2.1 Languages

Definition 2.1 An alphabet is a finite set of symbols. The set of all strings over a fixed alphabet \( X \) is denoted by \( X^* \). \( X^* \) includes the empty string \( e \). A subset \( L \subseteq X^* \) is called a language over alphabet \( X \).

We introduce some operations on languages. It is useful to recall the notions of substitution and homomorphism of languages [3]. A substitution \( f \) is a mapping of an alphabet \( \Sigma \) onto subsets of \( \Delta^* \) for some alphabet \( \Delta \). The substitution \( f \) is extended to strings by setting \( f(e) = e \) and \( f(ua) = f(u)f(a) \). An homomorphism \( h \) is a substitution such that \( h(a) \) is a single string for each symbol \( a \) in the alphabet \( \Sigma \).

1. Given a language \( L \) over alphabet \( X \cup V \), consider the
Definition 2.5 Let $L \subseteq (I \cup U)O^*$ over alphabet $I \cup U \cup O$ be $I^O$-progressive if for all prefixes $\alpha \in (I \cup U \cup O)^*$, $\forall i \in I \forall \beta \in (U \cup V)^* \exists y \in (U \cup V)^* \exists o \in O \{[\alpha \in L \Rightarrow \alpha \cdot i \cdot o \in L] \wedge [\alpha i \beta \in L \Rightarrow \alpha i \beta \cdot o \in L]\}$.

Definition 2.6 Let $L$ be a language over $I \cup O$ be $I^O$-defined if $L_{\delta I} = I^*$.

An $I^O$-progressive language is $I^O$-progressive, which in turn is $I_3$-defined. The converse of the two implications does not hold.

Definition 2.7 Let $L$ be a language over $X \cup U$ (X and U disjoint) is $U$-convergent if $\forall \alpha \in X^*$ the language $\alpha_{\delta U} \cap L$ is finite, otherwise it is $U$-divergent.

Example 2.1 Let $L = \{iu^*o\}$ where $X = \{i, o\}$ and $U = \{u\}$ is $U$-divergent, as witnessed by the string $io \in X$ whose expansion includes the infinite set $\{iu^*o\}$ coinciding with $L$.

2.2 Composition of Languages

Consider two systems $A$ and $B$ with associated languages $L(A)$ and $L(B)$. The systems communicate with each other by a channel $U$ and with the environment by channels $I$ and $O$. We introduce a composition operator that describes the external behaviour of the composition of $L(A)$ and $L(B)$.

Definition 2.8 Given alphabets $I, U, O$, language $L_1$ over $I \cup U$ and language $L_2$ over $U \cup O$, the parallel composition of languages $L_1$ and $L_2$ is the language $(L_1)_{\delta O} \cap (L_2)_{\delta I} |_{U \cup O}$, denoted by $L_1 \otimes L_2$. Given alphabets $I, U, O$, language $L_1$ over $I \cup U$ and language $L_2$ over $U \cup O$, the l-bounded parallel composition of languages $L_1$ and $L_2$ is the language $(L_1)_{\delta O} \cap (L_2)_{\delta I} |_{U \cup O}$, denoted by $L_1 \parallel L_2$, defined over $I \cup U$.

When $l = \infty$ the definition of l-bounded parallel composition reduces to the definition of parallel composition of languages, because then $(I \cup O)^*_{\delta (U,l)}$ becomes $(I \cup O)^*$, that is the universe over $I \cup O \cup U$, and so it can be dropped from the conjunction.

In the sequel it will be useful to consider the notion of $U$-convergence extended to the composition of two languages.

Definition 2.9 Given a language $A$ over alphabet $I \cup U$, a language $B$ over alphabet $U \cup O$ is $A$-compositionally $U$-convergent if the language $L = A_{\delta O} \cap B_{\delta I}$ over alphabet $X = (I \cup U) \cup U$ is $U$-convergent, i.e., $\forall \alpha \in (I \cup O)^*$ the language $\alpha_{\delta U} \cap L$ is finite.

When clear from the context, instead of $A$-compositionally we will write more simply compositionally.

2.3 Solution of Equations over Languages

2.3.1 Language Equations under Parallel Composition

Given pairwise disjoint alphabets $I, U, O$, languages $A$ over $I \cup U$ and $C$ over $I \cup O$, consider

$$A \diamond X \subseteq C.$$ (1)
3 Equations over Finite Automata

3.1 Finite Automata and Regular Expressions

Definition 3.1 A non-deterministic finite automaton (N DFA or simply FA) is defined as a 5-tuple \( F_A = (\Sigma, \Delta, \sigma, r, F) \). \( \Sigma \) represents the finite state space, \( \Delta \) represents the finite alphabet, and \( x \subseteq \Sigma \times \Sigma \times \{0, 1\} \) is the next state relation, such that \( n \in S \) is a next state of present state \( p \) on symbol \( i \in \Sigma \) if and only if \( (i, p, n) \in \Delta \). The initial or reset state is \( r \in S \) and \( F \subseteq S \) is the set of final or accepting states. A variant of NDFAs allows the introduction of \( \epsilon \)-moves, meaning that \( \Delta \subseteq (\Sigma \cup \epsilon) \times \Sigma \times S \).

The next state relation can be extended to have as argument strings in \( \Sigma^* \) (i.e., \( \Delta \subseteq \Sigma^* \times \Sigma \times S \)) as follows: \( (pi, s, s') \in \Delta \) if and only if there exists \( s' \in S \) such that \( (p, s, s') \in \Delta \) and \( (i, s', s'') \in \Delta \).

A string \( x \) is said to be accepted by the N DFA \( F_A \) if there exists a sequence of transitions corresponding to \( x \) such that \( \Delta(x, r) \) contains a state in \( F \). The language accepted by \( F_A \), designated \( L(F_A) \), is the set of strings \( \{x \mid \Delta(x, r) \cap F \neq \emptyset\} \).

For each present state \( p \) and symbol \( i \) there is at least one next state \( n \) such that \( (i, p, n) \in \Delta \) the N DFA is said to be complete.

A N DFA is a deterministic finite automaton (DFA) if for each present state \( p \) and symbol \( i \) there is exactly one next state \( n \) such that \( (i, p, n) \in \Delta \). The relation \( \Delta \) can be replaced by the next state function \( \delta \), defined as \( \delta : \Sigma \times S \rightarrow S \), where \( n \in S \) is the next state of present state \( p \in S \) on symbol \( i \in \Sigma \) if and only if \( n = \delta(i, p) \).

A string \( x \) is said to be accepted by the DFA \( F_A \) if \( \delta(x, r) \in F \). The language accepted by \( F_A \), designated \( L(F_A) \), is the set of strings \( \{x \mid \delta(x, r) \in F\} \).

The languages associated to finite automata are the regular languages and they are defined by means of regular expressions [3].

Definition 3.2 The sets denoted by regular expressions are the regular languages.

Regular languages are closed under union, concatenation, complementation and intersection. They are closed also under restriction, because they are closed under substitution [3]. We will show that they are closed under expansion, by providing an algorithm that, given the finite automaton of a language, returns the finite automaton of the expanded language.

3.2 Solution over Regular Languages

Non-deterministic finite automata are equivalent to deterministic ones and regular expressions are equivalent to finite automata [3]. By applying the algorithm of subset construction, one converts a N DFA into an equivalent complete DFA. Given an N DFA \( F_A = (\Sigma, \Delta, \sigma, r, F) \), the process of subset construction builds the DFA \( F_B = (2^\Sigma, \Delta, \delta, r, F_B) \), where 1) the states \( \delta \in 2^\Sigma \) are the subsets of \( \Sigma \), 2) the transition relation is \( \delta(i, s) = \cup_{s' \in \Sigma} \{s' \mid (i, s, s') \in \Delta \} \) and 3) a state is final, i.e., \( s \in F_B \subseteq 2^\Sigma \), if \( s \cap F \neq \emptyset \). Since many of the states in \( 2^\Sigma \) are unreachable from the initial state, they can be deleted. Thus, the determined automaton usually has fewer states than the power set. To make a N DFA complete, it is not necessary to apply the full-blown subset construction; it suffices to add a new non-accepting state \( s_d \) whose incoming transitions are
For all $i, s, s'$ for which there was no transition in the original automaton. By a closure construction [3], an N DFA with $\varepsilon$-moves can be converted to a N DFA without $\varepsilon$-moves; subset construction must be applied at the end to determinize it.

The equivalence of regular expressions and finite automata is shown by matching each operation on regular expressions with a constructive procedure that yields the finite automaton of the result, given the finite automata of the operands. For the most common operations (union, concatenation, complementation, intersection) see [3]. Here we sketch the procedures for restriction and expansion:

**restriction ($\|$)** Given FA $F_A$ that accepts language $L$ over $X \cup V$, the FA $F_A'$ that accepts language $L_{\|V}$ over $V$ is obtained by the following procedure:

1. $\forall x \in X \setminus V$, change every edge $(x, s, s')$ into the edge $(\epsilon, s, s')$, i.e., replace the symbols $x \in X \setminus V$ by $\epsilon$.
2. Apply the closure construction to obtain an equivalent finite automaton without $\epsilon$-moves and then apply subset construction to determinize it (even if the original FA $F_A$ was deterministic, the process of adding $\epsilon$-moves and then removing them by closure construction usually returns a N DFA).

**expansion ($\{\}$)** Given FA $F_A$ that accepts language $L$ over $X$, the FA $F_A'$ that accepts language $L_{\{V\}}$ over $X \cup V (X \cap V = \emptyset)$ is obtained by adding for each state $s, \forall v \in V$, the edge (self-loop) $(v, s, s)$.

**l-expansion ($\{\}$)** Given FA $F_A$ that accepts language $L$ over $X$, the FA $F_A'$ that accepts language $L_{\{V, 0\}, l}$ integer, over $X \cup V (X \cap V = \emptyset)$ is obtained as follows:

1. The set of states $S'$ of $F_A'$ is given by $S' = S \cup \bigcup_{s \in S} \{s^1, \ldots, s^l\}$.
2. The next state relation $\Delta'$ of $F_A'$ is given by
   $$\Delta' = \bigcup_{s \in S} \bigcup_{v \in V} \{(s, s', v)\} \cup \bigcup_{s \in S} \bigcup_{1 \leq j \leq l} \{(s^j, s^{j+1}, v)\} \cup \bigcup_{s, s' \in S} \bigcup_{1 \leq j \leq l} \{(s^j, s', x)\}$$
3. $r' = r$ and $F' = F$.

The procedure for restriction guarantees the substitution property $f(\epsilon) = \epsilon$.

**Theorem 3.1** There is an effective way to solve equations over regular languages.

**Proof.** Since all the operators used to express the solution of regular language equations have constructive counterparts on automata, then there is a constructive method for computing the solution. QED

The largest solution of parallel equations for prefix-closed regular languages was known already in the process algebra literature [7, 9, 6].

### 4 Finite State Machines

**Definition 4.1** A non-deterministic FSM (NDFSM), or simply an FSM or a machine, is defined as a 5-tuple $M = \langle S, I, O, T, r \rangle$ where $S$ represents the finite state space, $I$ represents the finite input space, $O$ represents the finite output space and $T \subseteq I \times S \times S \times O$ is the transition relation. On input $i$, the NDFSM at state $p$ may transit to $n$ and output $o$ if and only if $(i, p, n, o) \in T$. State $r \in S$ represents the initial or reset state. We denote the restriction of $T$ to $I \times S \times S$ (next state relation) by $T_n \subseteq I \times S \times S$, i.e., $(i, s, s') \in T_n \iff \exists o ((i, s, s', o) \in T)$; similarly, we denote the restriction of $T$ to $I \times S \times O$ (output relation) by $T_o \subseteq I \times S \times O$, i.e., $(i, s, o) \in T_o \iff \exists s' ((i, s', o) \in T)$. If at least one transition is specified for each present state and input pair, the FSM is said to be complete. If no transition is specified for some present state and input pair, the FSM is said to be partial. An FSM is said to be trivial when $T = \emptyset$.

It is convenient to think of the relations $T_n$ and $T_o$ as functions $T_n : I \times S \rightarrow 2^S$ and $T_o : I \times S \rightarrow 2^O$.

**Definition 4.2** An NDFSM is a pseudo non-deterministic FSM (PNDFSM) [1, 11], or observable FSM [10], if for each triple $(i, p, o) \in I \times S \times O$, there is exactly one state $n$ such that $(i, p, n, o) \in T$.

The qualification “non-deterministic” is because for a given input and present state, there may be more than one possible output; however, edges (i.e., transitions) carrying different outputs must go to different next states. The further qualification “pseudo” non-deterministic is because its underlying finite automaton is deterministic. In a PNDFSM the next state $n$ is unique for a given combination of input, present state and output, so it can be given by a next state function $n = T_n(i, p, o)$. Since the output is non-deterministic in general, it is represented by a relation $T_o \subseteq I \times S \times O$.

**Definition 4.3** A deterministic FSM (DFSM) is an NDFSM where for each pair $(i, p) \in I \times S$, there is at most one next state $n$ and one output $o$ such that $(i, p, n, o) \in T$, i.e., there is at most one transition from $p$ under $i$.

In a DFSM the next state $n$ and the output $o$ can be given, respectively, by a next state function $n = T_n(i, p)$ and an output function $o = T_o(i, p)$.

The transition relation $T$ of a NDFSM can be extended in the usual way to a relation on $I^* \times S \times S \times O^*$: given a present state $p$ and an input sequence $i_1 \ldots i_k \in I^*$, $(i_1 \ldots i_k, p, n_1 \ldots n_k) \in T$ if there is a sequence $s_1 \ldots s_{k+1}$ such that $s_1 = p$, $s_{k+1} = n$ and for each $j = 1, \ldots, k$ it holds that $(i_j, s_j, s_{j+1}, o_j) \in T$. A similar extension can be defined for $T_o$ and $T_n$.

In this paper FSMs are assumed to be pseudo non-deterministic, unless otherwise stated. Notice that it is always possible to convert a general NDFSM into a PNDFSM by subset construction.
4.1 Languages of FSMs

We now introduce the notion of language associated with an FSM. This is achieved by looking at the automaton underlying a given FSM. For our purposes, we define an associated language over the alphabet \( I \cup O \).

For a language over \( I \cup O \), the automaton is obtained from the original FSM, by replacing each edge labelled by \( i/o \) with an edge labelled by \( i \), followed by a new node (non-accepting state), followed by an edge labelled by \( o \). All original states are made accepting.

**Definition 4.4** Given an FSM \( M = (S, I, O, T, \tau) \), consider the finite automaton \( F(M) = (S \cup (S \times I), I \cup O, \Delta, \tau, S) \), where \( (i, s, (s, i)) \cup (s, i, s') \in \Delta \) iff \((i, s, s', o) \in T\). The language accepted by \( F(M) \) is denoted \( L^F(M) \), and by definition is the \( \cup \)-language of \( M \) at state \( \tau \). Similarly \( L^\tau(M) \) denotes the language accepted by \( F(M) \) when started at state \( s \), and by definition is the \( \cup \)-language of \( M \) at state \( s \). By construction, \( L_\tau(M) \subseteq (IO)^* \), where \( IO \) denotes the set \( \{o \mid i \in I, o \in O\} \).

\( \epsilon \in L_\tau(M) \) because the initial state is accepting. An FSM \( M \) is **trivial** iff \( L_\tau(M) = \epsilon \).

**Definition 4.5** A language \( L \) is an **FSM language** if there is an FSM \( M \) such that the associated automaton \( F(M) \) accepts \( L \). The language associated with a DFSM is sometimes called a **behaviour**.

**Remark** When convenient, we say that FSM \( M_A \) has property \( X \) if its associated FSM language has property \( X \).

**Definition 4.6** State \( t \) of FSM \( M_B \) is said to be a **reduction** of state \( s \) of FSM \( M_A \) (\( M_A \) and \( M_B \) are supposed to have the same input set), written \( t \preceq s \), if \( L(t) \preceq L(s) \). States \( t \) and \( s \) are **equivalent states**, written \( t \equiv s \), iff \( t \preceq s \) and \( s \preceq t \), i.e., when \( L(t) = L(s) \). States that are not equivalent are called **distinguishable**. An FSM whose states are all pairwise distinguishable is a **reduced FSM**.

Similarly, \( M_B \) is a **reduction** of \( M_A \), \( M_B \preceq M_A \), iff \( r_M \preceq r_{M_A} \), the initial state of \( M_B \) is a reduction of \( r_{M_A} \), the initial state of \( M_A \). When \( M_B \preceq M_A \) and \( M_A \preceq M_B \) then \( M_A \) and \( M_B \) are **equivalent machines**, i.e., \( M_A \equiv M_B \). Machines that are not equivalent are distinguishable.

For complete DFSMs reduction and equivalence of states coin-

cide. Given an FSM language, there is a family of equivalent FSMs associated to it; for simplicity we will usually talk of the FSM associated with a given FSM language. In this paper FSMs are assumed to be reduced, unless otherwise stated.

An FSM language is regular, whereas the converse is not true.

**Theorem 4.1** A regular language over alphabet \( I \cup O \) is the language of a complete FSM over input alphabet \( I \) and output alphabet \( O \) iff \( L \subseteq (IO)^* \). \( L \) is **IO-prefix-closed** and **IO-progressively**. A regular language \( L \subseteq (IO)^* \) that is IO-prefix-closed, but not IO-progressively, is the language of a partial FSM.

Given a regular language \( L \) over alphabet \( I \cup O \), the following algorithm builds \( L^{FSM} \), the largest subset of \( L \) that is the language of an FSM over input alphabet \( I \) and output alphabet \( O \).

**Procedure 4.1** Input: Regular language \( L \) over \( I \cup O \); Output: Largest FSM language \( L^{FSM} \) over \( I \cup O \).

1. Build a deterministic automaton \( A \) accepting \( L \cap (IO)^* \).
2. Delete the initial state if it is a nonfinal state.
3. Delete all nonfinal states having incoming edges labelled with symbols from alphabet \( O \), together with their incoming edges.
4. If the initial state has been deleted, then \( L^{FSM} = \emptyset \). Otherwise, let \( A \) be the automaton produced by the procedure and \( L^{FSM} \) the language that \( A \) accepts. If there is no outgoing edge from the initial state of \( A \), then \( A \) accepts the trivial language \( L^{FSM} = \{\epsilon\} \), otherwise it accepts a non-

trivial FSM language \( L^{FSM} \). Any FSM language in \( L \) must be a subset of \( L^{FSM} \).

To obtain the largest subset of \( L \) which is the language of a complete FSM we must apply one more pruning algorithm.

**Procedure 4.2** Input: FSM Language \( L^{FSM} \) over \( I \cup O \); Output: Largest IO-progressively FSM language \( Prog(L^{FSM}) \) over \( I \cup O \).

1. Build a deterministic automaton \( A \) accepting \( L^{FSM} \).
2. Iteratively delete all states that are final and for which \( \exists i \in I \) with no outgoing edge carrying the label \( i \), together with their incoming edges, until the initial state is deleted or no more state can be deleted. Delete the initial state if \( \exists i \in I \) with no outgoing edge carrying the label \( i \).
3. If the initial state has been deleted, then \( Prog(L^{FSM}) = \emptyset \). Otherwise, let \( A \) be the automaton produced by the procedure and \( Prog(L^{FSM}) \) the language that \( A \) accepts. Any I-progressive FSM language in \( L^{FSM} \) must be a subset of \( Prog(L^{FSM}) \).

**Proposition 4.1** An FSM whose language is \( L^{FSM} \) or \( Prog(L^{FSM}) \) can be trivially deduced from \( A \) by replacing pairs of consecutive edges labelled respectively with \( i \) and \( o \) by a unique edge labelled \( i/o \).

**Proposition 4.2** Given a regular language \( L \) over alphabet \( I \cup O \), let \( M \) be an FSM over input alphabet \( I \) and output alphabet \( O \). The language \( L(M) \) of \( M \) is contained in \( L \) if and only if \( L(M) \subseteq L^{FSM} \).

**Proof.** Show that \( L(M) \subseteq L \Rightarrow L(M) \subseteq L^{FSM} \). Indeed \( L(M) \) is an FSM language contained in \( L \) and \( L^{FSM} \) is by construction the largest FSM language contained in \( L \). So \( L(M) \subseteq L^{FSM} \), \( L(M) \subseteq L^{FSM} \Rightarrow L(M) \subseteq L \), since by definition \( L^{FSM} \subseteq L \). QED

\(^{1}\) The language associated with a ND FSM includes a set of behaviours.
4.2 Parallel Composition of FSMs

Different types of composition between pairs of FSMs may be defined, according to the protocol by which signals are exchanged. For a given composition operator and pair of FSMs we must establish whether that composition is defined, meaning that it yields a set of behaviours that can be described by another FSM. In general, the composition of FSMs is a partially specified function from pairs of FSMs to an FSM. In this paper we focus on the composition of FSMs by means of the parallel composition operator over languages introduced in Sec. 2. So the FSM yielded by the composition of FSMs $M_A$ and $M_B$ is the one whose language is obtained by the composition of the FSM languages associated with $M_A$ and $M_B$.

Consider the pair of FSMs $2$.

1. FSM $M_A$ has input alphabet $I_1 \cup V$, output alphabet $U \cup O_1$ and transition relation $T_A$;
2. FSM $M_B$ has input alphabet $I_2 \cup U$, output alphabet $V \cup O_2$ and transition relation $T_B$.

We define a parallel composition operator $\circ$ that associates with a pair of FSMs $M_A$ and $M_B$ another FSM $M_A \circ M_B$ such that:

1. the alphabet of the external inputs is $I_1 \cup I_2 = I$;
2. the alphabet of the external outputs is $O_1 \cup O_2 = O$.

Recall that, by definition of parallel composition of languages, $\alpha \in L(M_B) \circ L(M_A)$ iff

$$\alpha \in [L(M_B)_{I_1 \cup O_1} \cap L(M_A)_{I_2 \cup O_2}].$$

Notice that the expansions $L(M_B)_{I_1 \cup O_1}$ and $L(M_A)_{I_2 \cup O_2}$ are needed to have the languages of $M_B$ and $M_A$ defined on the same alphabet.

**Lemma 4.1** If $L(M_A)$ and $L(M_B)$ are FSM $\cup$-languages, then $L(M_A) \circ L(M_B)$ is an FSM $\cup$-language.

**Proof.** $L(M_A) \circ L(M_B)$ is prefix-closed, because prefix-closed $\cup$-languages are closed under $\circ$ composition. Indeed, a state of the finite automaton corresponding to an FSM $\cup$-language is accepting iff it is the initial state or all its ingoing edges are labelled by symbols in $O$. The property is preserved by intersection and restriction over $I \cup O$. The intersection with $(I \cup O)^*$ makes sure that in the strings of the resulting FSM $\cup$-language an input is always followed by exactly one output, so that a corresponding FSM (with edges labelled by pairs $(i/o)$) can be reconstructed. Notice that $L(M_A) \circ L(M_B)$ does not need to be progressive, because partial FSMs are allowed. QED

Therefore we can state the following definition.

**Definition 4.7** The parallel composition of FSMs $M_B$ and $M_A$ yields the FSM $M_A \circ M_B$ with language

$$L(M_A \circ M_B) = L(M_A) \circ L(M_B) \cap (I \cup O)^*.$$

If the language $L(M_A) \circ L(M_B) \cap (I \cup O)^* = \{\epsilon\}$, then $M_A \circ M_B$ is a trivial FSM.

The previous definition is sound because the language $L(M_A) \circ L(M_B) \cap (I \cup O)^*$ by Lemma 4.1 is an FSM language, which may correspond to a complete or partial FSM according to whether the language $L(M_A) \circ L(M_B) \cap (I \cup O)^*$ is $I \cup O$-progressive or not. Then by subset construction and reduction we produce a reduced observable FSM. In summary, we convert from the FSMs $M_B$ and $M_A$ to the automata accepting their FSM languages, operate on them and then we convert back from the resulting automaton to an FSM; then we produce a reduced PNDFSM (we assume that $M_B$ and $M_A$ are PNDFSMs).

4.3 Solutions of Equations over FSMs

Consider a general interconnection of two FSMs $M_A$ and $M_B$, where FSM $M_A$ has input signals $I_1$ and $V$ and output signals $U$ and $O_1$, and FSM $M_B$ has input signals $I_2$ and $U$ and output signals $V$ and $O_2$. The network implements a specification $M_C$ with input signals $I_1, I_2$ and output signals $O_1, O_2$. Suppose that $M_A$ and $M_C$ are known and $M_B$ is unknown, we want to define an equation of the type $M_A \circ M_X \leq M_C$, to capture the FSMs $M_B$ that in place of $M_X$ let the network of $M_A$ and $M_B$ match the specification $M_C$. Through Definition 4.4 we have seen a way to associate an FSM language to a given FSM, and the related composition operator $\circ$ has been introduced in Sec. 4.2; therefore we introduce the following equation over FSMs:

$$M_A \circ M_X \leq M_C,$$

and solve it by building first the related language equation $L(M_A) \circ L(M_X) \subseteq L(M_C) \cup (I \cup O)^*$. When there is no ambiguity $A \circ X \subseteq C \cup (I \cup O)^*$ denotes the language equation $L(M_A) \circ L(M_X) \subseteq L(M_C) \cup (I \cup O)^*$.

Given alphabets $I_1, I_2, U, V, O_1, O_2$, an FSM $M_A$ over inputs $I_1 \cup V$ and outputs $U \cup O_1$, and an FSM $M_C$ over inputs $I_1 \cup I_2$ and outputs $O_1 \cup O_2$, consider the FSM equation

$$M_A \circ M_X \leq M_C,$$

whose unknown is an FSM $M_X$ over inputs $I_2 \cup U$ and outputs $V \cup O_2$. We will use the shortened notation $I = I_1 \cup I_2$ and $O = O_1 \cup O_2$.

**Definition 4.8** FSM $M_B$ is a solution of the equation $M_A \circ M_X \leq M_C$, where $M_A$ and $M_C$ are FSMs, if and only if $M_A \circ M_B \leq M_C$.

Converting to the related FSM languages, we construct the associated language equation

$$L(M_A) \circ L(M_X) \subseteq L(M_C) \cup (I \cup O)^*,$$

where $L(M_A)$ is over $I_1 \cup U \cup V \cup O_1$, $L(M_C)$ is over $I_1 \cup I_2 \cup O_1 \cup O_2$ and the unknown FSM language is over $I_2 \cup U \cup V \cup O_2$. The previous equation can be rewritten for simplicity as

$$A \circ X \subseteq C \cup (I \cup O)^*.$$
We want to characterize solutions that are FSM languages. We know from Theorem 2.1 that the largest solution of $A \circ X \subseteq C \cup \{\text{IO}\}^*$ is the language $S = A \circ (C \cap \{\text{IO}\}^*)$, if $S \neq \emptyset$.

In general $S$ is not an FSM language. To compute the largest FSM language contained in $S$, $S_{FSM}$, we must compute the largest prefix-closed language contained in $S \cap ((I_2 \cup U) (V \cup O_2))^*$.

**Theorem 4.2** Let $A$ and $C$ be FSM languages. The largest FSM language solution of the equation $A \circ X \subseteq C \cup \{\text{IO}\}^*$ is denoted by $S_{FSM}$, where $S = A \circ (C \cap \{\text{IO}\}^*)$. If $S = \emptyset$ then $S_{FSM} = \emptyset$; if $S \neq \emptyset$, $S_{FSM}$ is obtained by applying Procedure 4.1 to $S$. If $S_{FSM} = \emptyset$ then the FSM language equation $A \circ X \subseteq C \cup \{\text{IO}\}^*$ has no solution.

**Proof.** The first step of Procedure 4.1 computes the intersection of $S$ with $((I_2 \cup U) (V \cup O_2))^*$ to enforce that the solution, if it exists, is an FSM language with input alphabet $I_2 \cup U$ and output alphabet $V \cup O_2$. Since $A$ and $C$ are regular languages, $S \cap ((I_2 \cup U) (V \cup O_2))^*$ is regular too, and, by construction, Procedure 4.1 extracts the largest FSM language contained in it. QED

By Proposition 4.1, it is easy to derive an FSM $M_{FSM}$ associated with $S_{FSM}$. This allows us to talk about FSMs that are solutions of FSM equations, meaning any reduction of the FSM $M_{FSM}$, as guaranteed by Prop. 4.2.

For logic synthesis applications, we assume that $M_\ell$ and $M_C$ are complete FSMs and we require the solution is a complete FSM too. This is obtained by applying Procedure 4.2 to $S_{FSM}$, yielding $Proc(S_{FSM})$, the largest $(I_2 \cup U)(V \cup O_2)$-progressive FSM language $\subseteq ((I_2 \cup U) (V \cup O_2))^*$.

**Proposition 4.3** FSM $M_{FSM}$ is a solution of the equation $A \circ M \subseteq M_C$, where $M_A$ and $M_C$ are FSMs, if and only if $M_{FSM}$ is a reduction of the FSM $M_{FSM}$ associated with $S_{FSM}$, where $S_{FSM}$ is obtained by applying Procedure 4.1 to $S$, where $S = A \circ (C \cap \{\text{IO}\}^*)$. If $S_{FSM} = \emptyset$ then no FSM is a solution. The largest complete FSM solution $M_{Proc(S_{FSM})}$ is found, if it exists, by Procedure 4.2. A complete FSM is a solution if and only if it is a reduction of the largest complete solution $M_{Proc(S_{FSM})}$.

Furthermore, we restrict the attention to the solutions $B$ such that $A_{I_2 \cup O_2} \cap B_{\emptyset I_1 \cup O_1} \cap \{\text{IO}\}^*_{\emptyset U \cup V}$ is an $I^*\text{O}$-progressive FSM language $\subseteq (I(U \cup V)^*O)^*$ and so the composition is a complete FSM over inputs $I_1 \cup I_2$ and outputs $O_1 \cup O_2$. Since $A_{I_2 \cup O_2} \cap B_{\emptyset I_1 \cup O_1} \cap \{\text{IO}\}^*_{\emptyset U \cup V}$ is $I^*\text{O}$-prefix-closed, it corresponds to a partial FSM. We have to restrict it so that it is also $I^*\text{O}$-progressive, which corresponds to a complete FSM.

To now discuss the issue of progressiveness and livelocks (endless cycles of internal actions).

**Definition 4.9** A solution $B$ of Eq. 5 is $A$-compositionally $I^*\text{O}$-progressive if $A_{I_2 \cup O_2} \cap B_{\emptyset I_1 \cup O_1} \cap \{\text{IO}\}^*_{\emptyset U \cup V}$ is $I^*\text{O}$-progressive.

If $B$ is compositionally $I^*\text{O}$-progressive, the restriction to $I \cup O$ of the composition is an $I^*\text{O}$-progressive language, meaning that its corresponding FSM is complete.

**Definition 4.10** A solution $B$ of Eq. 5 is $A$-compositionally $I^*\text{O}$-progressive if $A_{I_2 \cup O_2} \cap B_{\emptyset I_1 \cup O_1} \cap \{\text{IO}\}^*_{\emptyset U \cup V}$ is $I^*\text{O}$-progressive.

A compositionally $I^*\text{O}$-progressive solution yields a composition that has no $(u \cup v)^*$ cycles without exit. Such a solution is also compositionally $I^*\text{O}$-progressive, but the converse does not hold.

**Definition 4.11** A solution $B$ of Eq. 5 is $A$-compositionally prefix $(U \cup V)$-convergent (abbreviated as $A$-compositionally $(U \cup V)$-convergent) if $A_{I_2 \cup O_2} \cap B_{\emptyset I_1 \cup O_1} \cap \{\text{IO}\}^*_{\emptyset U \cup V}$ is $(U \cup V)$-convergent.

A compositionally $(U \cup V)$-convergent solution yields a composition that has no $(u \cup v)^*$ cycles, i.e., it is livelock-free. A compositionally $I^*\text{O}$-progressive or compositionally prefix $I^*\text{O}$-progressive solution does not need to be compositionally $(U \cup V)$-convergent.

**Theorem 4.3** Let $B$ be an $(I_2 \cup U)(V \cup O_2)$-progressive solution of $A \circ X \subseteq C \cup \{\text{IO}\}^*$ and let $A = (I_1 \cup U)(V \cup O_1)$ be progressive. If $B$ is compositionally prefix $(U \cup V)$-convergent, then $B$ is compositionally prefix $I^*\text{O}$-progressive.

**Proof.** Since the components $A$ and $B$ are progressive their composition $Init(A)_{I_2 \cup O_2} \cap Init(B)_{\emptyset I_1 \cup O_1} \cap Init((\{\text{IO}\}^*)_{\emptyset U \cup V}$ is deadlock-free, i.e., it never stops because a component does not have a transition under a given input. If the composition is also $(U \cup V)$-convergent, there can be no livelocks, i.e., there are no cycles labeled with actions from the set $U \cup V$. Therefore an external input, after a finite path labelled with internal actions, must be followed by an external output. QED

If $S_{FSM}$ is compositionally prefix $I^*\text{O}$-progressive, then it is the largest compositionally prefix $I^*\text{O}$-progressive solution of the equation. However, not every non-empty subset of $S_{FSM}$ inherits this feature. If $S_{FSM}$ is not compositionally prefix $I^*\text{O}$-progressive, then denote the largest compositionally prefix $I^*\text{O}$-progressive subset of $S_{FSM}$ by $c^*\text{O}ProcInit(S_{FSM})$. Conceptually $c^*\text{O}ProcInit(S_{FSM})$ is obtained from $S_{FSM}$ by deleting each string $a \in (I(U \cup V)^*O)^*$ such that, for some $i \in I$, there is no $(u \cup v)^* \in (U \cup V)^*$ and no $o \in O$ for which it holds $a i(u \cup v)^* o \in Init(A)_{I_2 \cup O_2} \cap Init(S_{FSM})_{\emptyset I_1 \cup O_1} \cap Init((\{\text{IO}\}^*)_{\emptyset U \cup V}$. We designed a procedure (not reported here) to compute the largest compositionally prefix $I^*\text{O}$-progressive solution.

Moreover we may require that the solutions are compositionally $(U \cup V)$-convergent (see Definition 2.7), to rule out all livelocks from the composition. However, when $S_{FSM}$ is not compositionally $(U \cup V)$-convergent, then the largest $(U \cup V)$-convergent solution does not exist and each finite $I^*\text{O}$-prefix-closed subset of $S_{FSM}$ is a compositionally $(U \cup V)$-convergent solution; thus no such sequence can be deleted from the largest solution without missing a compositionally $(U \cup V)$-convergent solution.
4.4 Bounded Parallel Composition of FSMs

Here we discuss the solutions whose composition with the context produces an external output after at most $l$ internal actions and provide the key steps to solve FSM equations under bounded parallel composition.

**Definition 4.12** The $b$-bounded parallel composition of FSMs $M_B$, over input alphabet $I_2 \cup U$ and output alphabet $O_2 \cup V$, and of $M_A$, over input alphabet $I_1 \cup V$ and output alphabet $O_1 \cup U$, yields the FSM $M_A \circ_l M_B$ with language

$$L(M_A \circ_l M_B) = L(M_A) \circ_l (L(M_B) \cap (IO)^*)$$

$$= [L(M_A) \circ_l (U \cup V)] \circ_l (L(M_B) \circ_l (U \cup V) \cap (IO)^*)$$

$$\cap (I \cup O)^* \cap (I \cup O)^* \cap (IO)^*.$$  

When $l = \infty$, this reduces to parallel composition of FSMs.

**Proposition 4.4** FSM $M_B$ is a solution of the equation $M_A \circ_l M_X \preceq M_C$, where $M_A$ and $M_C$ are FSMs, if and only if $M_B$ is a reduction of the FSM $M_{SFSM}$ associated with $S_{FSM}$, where $S_{FSM}$ is obtained by Procedure 4.1 to $S$, where $S = (A \circ_l (U \cup V) \cap (IO)^*) \circ_l (I \cup O)^* \cap (I \cup O)^* \cap (IO)^*$. If $S_{FSM} = \emptyset$ then no FSM is a solution. $S_{FSM}$ is the largest compositionally (U \cup V)-convergent solution of $M_A \circ_l M_X \preceq M_C$. The largest complete FSM solution $M_{Prop}(S_{FSM})$ is found, if it exists, by Procedure 4.2.

**Theorem 4.4** A solution $M_B$ of $M_A \circ_l M_X \preceq M_C$ is also a compositionally (U \cup V)-convergent solution of $M_A \circ M_X \preceq M_C$.

If $M_A$ and $M_B$ are also complete, then $M_B$ is a compositionally prefix $\ast$-progressive and compositionally $\ast$-progressive solution of $M_A \circ M_X \preceq M_C$.

**Proof.** By construction, a solution $M_B$ of $M_A \circ_l M_X \preceq M_C$ is compositionally (U \cup V)-convergent. A solution $M_B$ of $M_A \circ_l M_X \preceq M_C$ is also a solution of $M_A \circ M_X \preceq M_C$, because when $l = \infty$ the operator $\circ_l$ becomes the operator $\circ$.

By Theorem 4.3, the fact that $M_B$ is compositionally (U \cup V)-convergent, together with the completeness of $M_A$ and $M_B$, imply that $M_B$ is compositionally prefix $\ast$-progressive and therefore compositionally $\ast$-progressive. QED

However, $M_A \circ M_X \preceq M_C$ may be solvable even though $M_A \circ_i M_X \preceq M_C$ has no solution. This may happen when $M_A \circ M_X \preceq M_C$ has no compositionally $\ast$-progressive solution. If $M_A \circ_l M_X \preceq M_C$ has no complete solution, it is open whether there is a compositionally $\ast$-progressive solution.

5 Conclusions

We addressed the problem of finding an unknown component in a network in order to satisfy a global system specification. In this paper we addressed only the parallel language equation $A \circ X \subseteq C$ and provided solutions and algorithms for classes of automata and constrained versions of the problem. In particular we showed how to compute the largest FSM language that is a solution of the language equation $A \circ X \subseteq C$, the largest complete solution, and the largest solution whose composition with the context $A$ yields a complete FSM language.

We applied these techniques to a classical synthesis’ problem of a converter between a given mismatched pair of protocols, using their specifications, and those of the channel and the user services. The problem was addressed in [5, 2] with supervisory control techniques. We were able to derive the largest solution, and the largest compositionally progressive solution, which were not previously reported in the literature.

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